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June 1986

UWFDM-712

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1. Introduction

Light ion beam driven inertial confinement fusion (ICF) requires that megaamperes of current in the form of light ions (protons through carbon) be focused onto a fusion target about 1 cm in diameter.⁽¹⁾ Ballistic focusing of such large particle currents is only possible over relatively short distances (~ 20 -50 cm) due to space charge forces. Although this ion-diode ballistic focusing is the basis of today's light ion fusion experiments it must be replaced by ion propagation over standoff distances of several meters for the high yield experiments and reactors of the future.

One proposed scheme for propagating ions is depicted in Fig. 1. The ions are focused from an extraction diode over a short distance into the entrance of a preformed z-pinch plasma channel.⁽²⁾ A number of these channels (~ 8 -20) terminate at the target in the center of the chamber. Ions from an individual diode propagate down the plasma channel, confined by the B_θ azimuthal magnetic field in the z-pinch plasma. The plasma has high enough conductivity to charge and current neutralize the ion beam. Understanding the formation of these plasma channels and the propagation dynamics of the ion beam in this background magnetized plasma is vital to the success of light ion driven fusion reactor applications.

The complete analysis of this ion propagation demands the solution of Maxwell's equations along with models of the ion beam itself and the background plasma. The delicate interaction of these three components can lead to macroscopic instabilities such as the sausage and hose instabilities and to microscopic instabilities such as the two stream instability or to beam filamentation.^(3,4) Theoretical analysis of these instability issues has led to a set of instability threshold criteria⁽⁵⁾ that have been implemented in a code

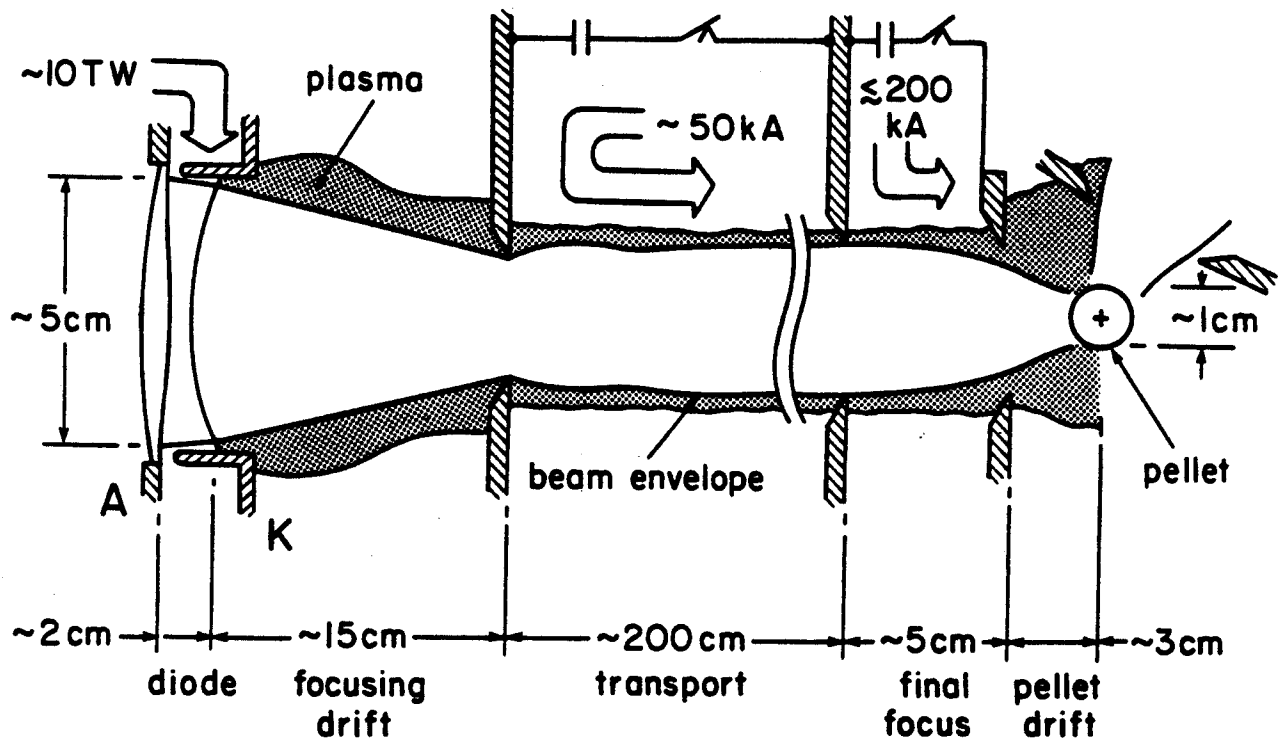


Fig. 1. Z-Pinch plasma channel.

called WINDOW (FENSTER).⁽⁶⁾ This code determines the "window" in parameter space where beams are thought to propagate, free of instabilities that might destroy the beam.

The ION code, described in this report, determines the trajectories of individual ions in a plasma channel assuming that the ideal conditions of perfect space charge and current neutralization are in effect. The only forces on the ions are the magnetic field due to the current driven through the channel plasma by an external circuit. By stochastically injecting ions into the channel according to some radial and angular distribution the ION code can graphically determine the envelope of the beam made up of these ions. This will allow the determination of the transport efficiency for varying diode focusing parameters and for different magnetic field configurations in the channel. The code is written in a modular fashion in standard FORTRAN 77 and can be easily modified to add new effects or to measure different beam parameters.

Section 2 of this report outlines the theoretical bases for the methods used in the code. Section 3 describes the features in the code. In the Appendix is a listing of the ION code and a description of two IMSL library routines used by the code.

2. Method of Solution

There are three different ion trajectory models implemented in the ION code. The first two are analytic in nature and are taken from the paper by Ottinger, Mosher, and Goldstein, "Propagation of Intense Ion Beams in Straight and Tapered Z-Discharge Plasma Channels," Ref. 7. The third model uses a numerical integration of the equations of motion of the ion in an arbitrary mag-

netic field allowing nonzero angular momentum of the ions. Each of these will be briefly discussed in the following three subsections.

2.1 Axially Uniform Plasma Channel

An axially uniform plasma channel (confusingly called a "straight" channel in Ref. 7) with a radially uniform current density results in an azimuthal magnetic field of the form

$$\begin{aligned} B_{\theta} &= B_0 r/r_c & r < r_c \\ B_{\theta} &= B_0 r_c/r & r > r_c \end{aligned}$$

where r_c is the radius of the uniform current profile and B_0 is the magnetic field at this radius. The equations of motion for an ion of mass m_i and charge Q in this linear magnetic field are

$$\begin{aligned} \ddot{r} &= -\omega_{cb}^2 \dot{z} r/r_c \\ \ddot{z} &= \omega_{cb}^2 \dot{r} r/r_c \end{aligned}$$

where the beam cyclotron frequency is

$$\omega_{cb} = QeB_0/m_i c .$$

It is assumed that there is no angular momentum component to the ion motion. Approximate solutions to these equations can be obtained for the condition $\dot{r}/\dot{z} \ll 1$ (i.e., the ions are injected at a shallow angle of injection). The initial conditions for these equations of motion are shown in Fig. 2. The approximate analytic solutions are⁽⁷⁾

ION ORBIT INITIAL CONDITIONS

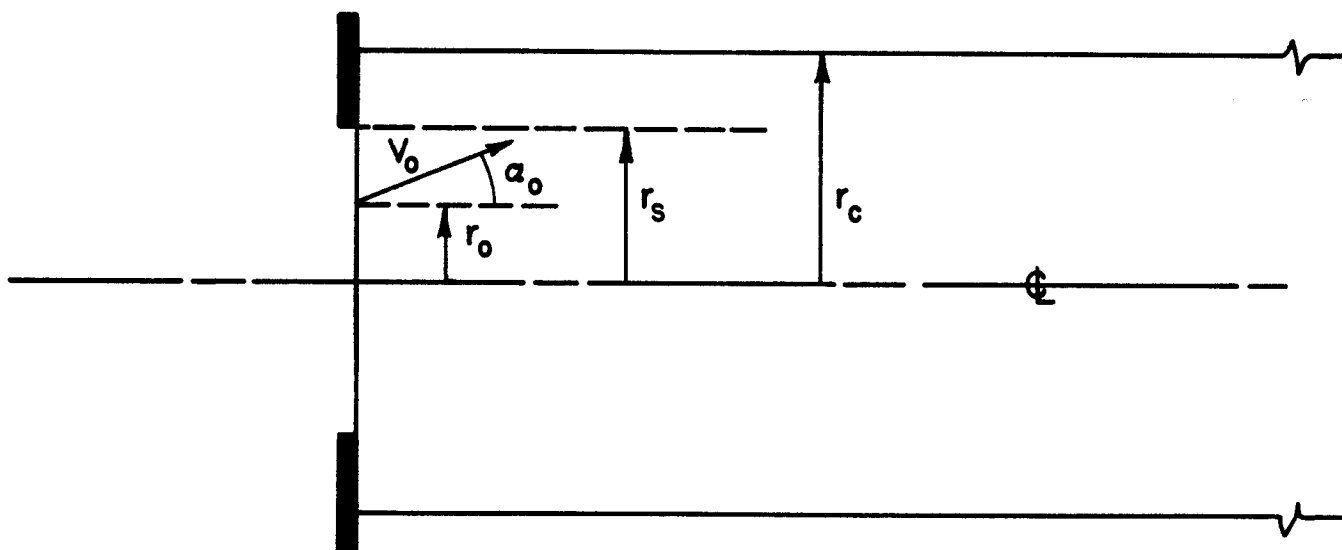


Fig. 2. Initial conditions for ion injection into a Z-Pinch plasma channel with no angular momentum.

$$z(t) = (V_0 \cos \alpha_0 - \frac{\omega_{cb} \bar{r}^2}{4r_c} \cos 2\phi) t$$

$$+ \frac{\bar{r}^2}{8r_c} \left(\frac{r_c \omega_{cb}}{V_0 \cos \alpha_0} \right)^{1/2} [\sin 2(\omega_{\beta} t + \phi) - \sin 2\phi] + O(\epsilon^3)$$

$$r(t) = \bar{r} \cos (\omega_{\beta} t + \phi) + O(\epsilon^3)$$

where

$$\omega_{\beta} = \Omega \left(1 - \frac{\omega_{cb} \bar{r}^2}{16 r_c V_0 \cos \alpha_0} + \frac{\tan^2 \alpha_0}{4} \right)$$

$$\tan \phi = - \left(\frac{r_c V_0 \cos \alpha_0}{\omega_{cb} \cos \alpha_0} \right)^{1/2} \tan \alpha_0$$

$$\bar{r} = \left(r_0^2 + \frac{r_c V_0 \sin^2 \alpha_0}{\omega_{cb} \cos \alpha_0} \right)^{1/2}$$

$$\Omega = (\omega_{cb} V_0 \cos \alpha_0 / r_c)^{1/2} = \text{betatron frequency}$$

V_0 = constant speed of ion

α_0 = angle of injection into the channel

$$r(0) = r_0 \quad \dot{r}(0) = V_0 \sin \alpha_0$$

$$z(0) = 0 \quad \dot{z}(0) = V_0 \cos \alpha_0$$

These conditions demand that the channel current satisfy⁽⁷⁾

$$I_0 > (1.57 \times 10^7 \frac{m_i/m_p}{Q} \alpha_m^2 V_0 / c) (1 - r_s^2 / r_c^2)^{-1} \text{ amps}$$

to confine ions with a maximum injection angle of α_m , where m_p is the proton mass.

2.2 Tapered Plasma Channel

If the channel radius is assumed to decrease linearly along its length such that

$$r_c(z) = r_c(1 - z/L) ,$$

then
$$B_\theta = \frac{2I_0 r}{cr_c^2(1 - z/L)^2} \quad r < r_c(1 - z/L)$$

where L is the taper length, r_c is the channel radius at $z = 0$ and this expression only applies for

$$(L - z)^2 \gg r^2 .$$

In this case the equations of motion for an ion take the form

$$\ddot{r} = - \frac{\omega_{cb} \dot{z} r}{r_c(1 - z/L)^2}$$

$$\ddot{z} = \frac{\omega_{cb} \dot{r} r}{r_c(1 - z/L)^2}$$

where

$$\omega_{cb} = \frac{2 QeI_0}{m_i c^2 r_c} .$$

Again, for $\dot{r}/\dot{z} \ll 1$, these equations may be solved approximately to give the ion orbit as⁽⁷⁾

$$z(t) = v_0 t + O(\epsilon^2)$$

$$r(t) = r_0(1 - t/T)^{1/2} \cos[-\Omega T \ln(1 - t/T)] \\ + (v_0 \sin \frac{\alpha_0}{\Omega})(1 - t/T)^{1/2} \sin[-\Omega T \ln(1 - t/T)] + O(\epsilon^2)$$

where

$$T = L/v_0$$

$$\Omega^2 = \omega_{cb} v_0 / r_c$$

$$r(0) = r_0 \quad \dot{r}(0) = v_0 \alpha_0$$

$$\dot{z}(0) = v_0$$

$$\alpha_0 \ll 1 \quad \text{and} \quad (\Omega T)^{-1} \ll 1 .$$

2.3 Arbitrary $B_0(r, z)$ and Nonzero Angular Momentum

Rather than using either of the previous approximate analytic solutions to the ion orbit equations one can simply solve the differential equations that describe the ion motion. This is done for the general case of ions with nonzero angular momentum. This is shown schematically in Fig. 3. The previous solutions (with zero angular momentum) are solved for the "in-plane" motion of the ions because there was no component of velocity out of the r - z plane. For the purposes of simulation the r - z plane "in-plane" can always be chosen as the x - z plane. Then v_y will represent the out-of-plane velocity component.

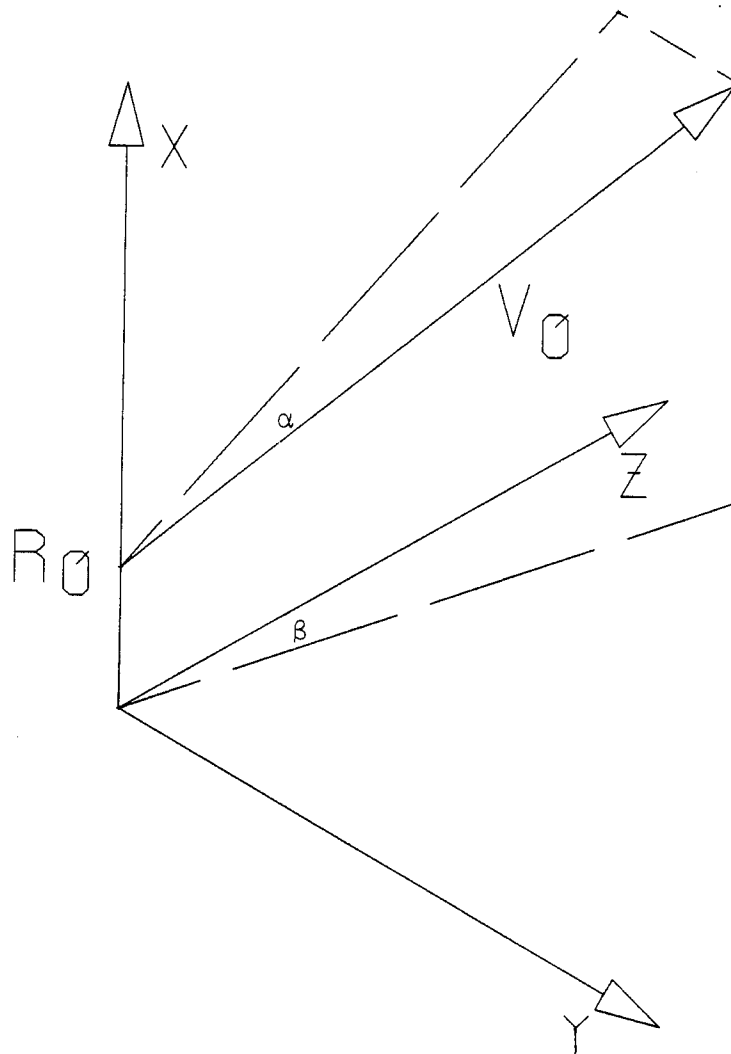


Fig. 3. Initial conditions for ion injection into a Z-Pinch plasma channel including angular momentum.

The equations of motion are

$$\ddot{x} = \frac{Qe}{mc} (\dot{y}B_z - \dot{z}B_y)$$

$$\ddot{y} = \frac{Qe}{mc} (\dot{x}B_z - \dot{z}B_x)$$

$$\ddot{z} = \frac{Qe}{mc} (\dot{x}B_y - \dot{y}B_x)$$

with

$$x(0) = r_0 \quad \dot{x}(0) = v_0 \sin \alpha_0$$

$$y(0) = 0 \quad \dot{y}(0) = v_0 \cos \beta_0$$

$$z(0) = 0 \quad \dot{z}(0) = v_0 \cos \alpha_0$$

$$r_0 = f_{r_0}(x/r_s) \quad \text{Gaussian distribution}$$

$$\alpha_0 = f_{\alpha_m} \quad \text{uniform distribution } [-\alpha_m, \alpha_m]$$

$$\beta_0 = f_{\beta_m} \quad \text{uniform distribution } [-\beta_m, \beta_m]$$

These equations are posed as six first order O.D.E.'s

$$\dot{x}_1 = x_2 \quad \dot{x}_2 = \frac{Qe}{mc} (x_4 B_z - x_6 B_y)$$

$$\dot{x}_3 = x_4 \quad \dot{x}_4 = \frac{Qe}{mc} (x_2 B_z - x_6 B_x)$$

$$\dot{x}_5 = x_6 \quad \dot{x}_6 = \frac{Qe}{mc} (x_2 B_y - x_4 B_x)$$

and solved using a standard fifth order predictor-corrector solver. For $\beta_m = 0$ these equations default to the zero angular momentum equations. The subroutine BXYZ can be modified by the user to give arbitrary magnetic fields. For

$$B_\theta(r) = B_0 (r/r_c)^n$$

the expressions for B_x and B_y are given below

$$B_x/B_\theta = \sin \theta \quad B_x = B_\theta \sin \theta$$

$$B_y/B_\theta = \cos \theta \quad B_y = B_\theta \cos \theta$$

$$B_x = B_\theta y/r \quad r = \sqrt{x^2 + y^2}$$

$$B_y = B_\theta x/r \quad B_\theta = B_0 \left(\frac{x^2 + y^2}{x_c^2} \right)^{n/2}$$

hence

$$B_x = B_0 \left(\frac{x^2 + y^2}{x_c^2} \right)^{n/2} \frac{y}{\sqrt{x^2 + y^2}} = B_0 (x^2 + y^2)^{(n-1)/2} \frac{y}{x_c^n}$$

$$B_y = B_0 \left(\frac{x^2 + y^2}{x_c^2} \right)^{n/2} \frac{x}{(x^2 + y^2)^{1/2}} = B_0 \frac{(x^2 + y^2)^{(n-1)/2}}{x_c^n} x .$$

For the case of uniform current (hence linear B_θ) we get

$$B_x = B_0 y/x_c ,$$

$$B_y = B_0 x/x_c .$$

This is the default in the program.

3. The ION Code

The ION code is structured according to the three different ion orbit models discussed in Section 2. A structure chart of the code is given in Fig. 4. Each different model is completely self-contained within the code. New models can be easily added by changing the main program and adding a new subroutine. Variable names conform to this report and Ref. 7. The code calls two IMSL library routines, for random numbers (GGUBFS) and the differential equation solver (DGEAR). The code is designed to be run interactively with free format input for which the user is prompted, but can be run in batch mode as well. Output is mostly to files that may be post-processed for plotting. The format of the files is given in Table 1.

3.1 Features

There are three different output options for each of the three orbit models, thus providing nine different kinds of calculations. These three output options are:

Table 1. Format of Output Files to Use for Plotting

Output Option			
<u>(ICALC)</u>	<u>Variable</u>	<u>Description</u>	<u>Format</u>
1	NPTS	Number of (z,r) points	I10
	Z(I), R(I)	(z,r) points	1P12E10.2
	I=1, NPTS		
2	NM1	Number of (z,r) points	I10
	Z(I), R(I)	(z,r) points	1P12E10.2
	I=1, NM1		
3	NZFIX	Number of planes at which distributions are computed	I10
	RHIST(J,K)	Radii for bins where	1P10E10.2
	((J=1,10),K=1,NZFIX)	particles are tallied.	
	PHIST(J,K)	Particles tallied in each	1P10E10.2
	((J=1,10),K=1,NZFIX)	bin.	
	FHIST(J,K)	Fluence of particles	1P10E10.2
	((J=1,10),K=1,NZFIX)	tallied in each bin.	

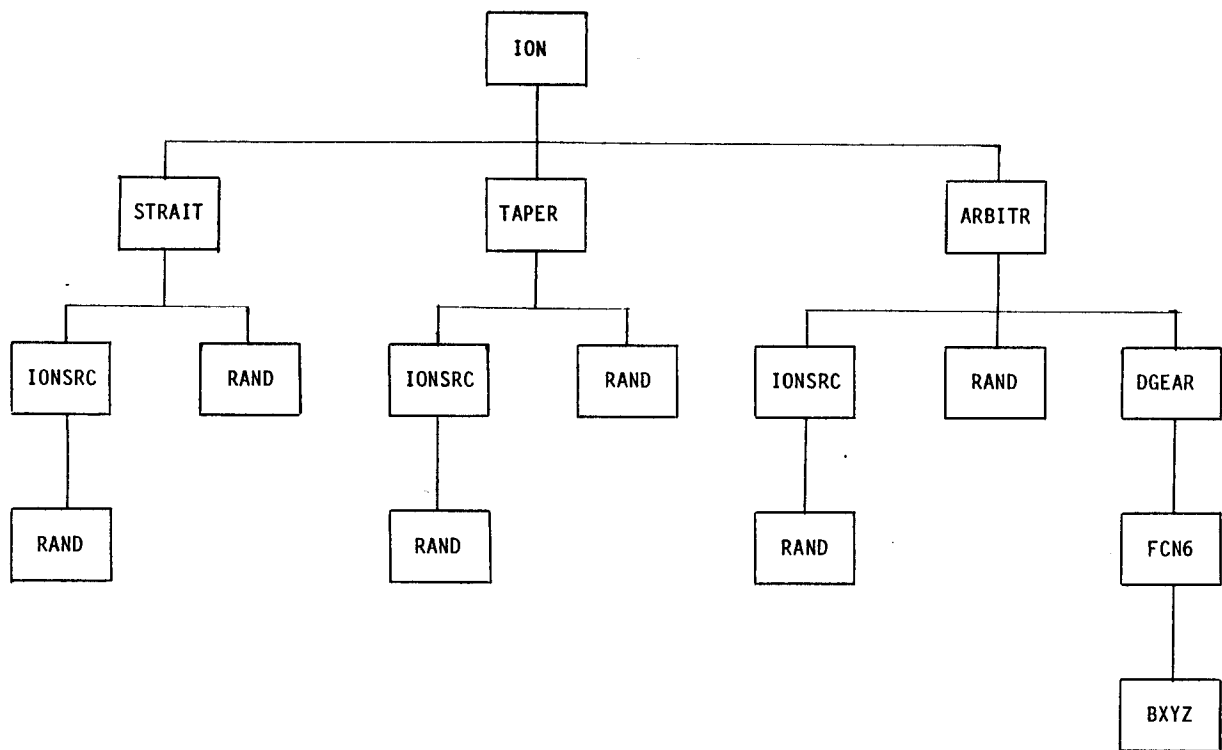


Fig. 4. Structure chart of the ION code.

1. trace the trajectory of ions for a specified length of time;
2. show the positions of all ions at a selected instant in time;
3. plot the radial profile of ions as they pass through a plane at a specified position in the channel.

Other output options can be easily added to each orbit model by including another ELSE IF statement in the appropriate subroutine.

In all cases the ions are randomly injected into the channel in a Gaussian distribution in radius and a uniform distribution in angle. These are shown in Fig. 5. The initial radius r_0 is selected by sampling the distribution

$$r_0 = r_s \sqrt{-2 \ln \xi}$$

and the angle of injection and the out of plane angle are selected by sampling

$$\alpha_0 = \alpha_m (1 - 2\xi)$$

$$\beta_0 = \beta_m (1 - 2\xi)$$

where ξ is a random number uniformly distributed in the interval $[0,1]$. The code uses pseudo-random numbers since the same initial seed number will produce the same sequence of random numbers.

Acknowledgment

This work was supported in part by contracts from Kernforschungszentrum Karlsruhe and Sandia National Laboratory, Albuquerque.

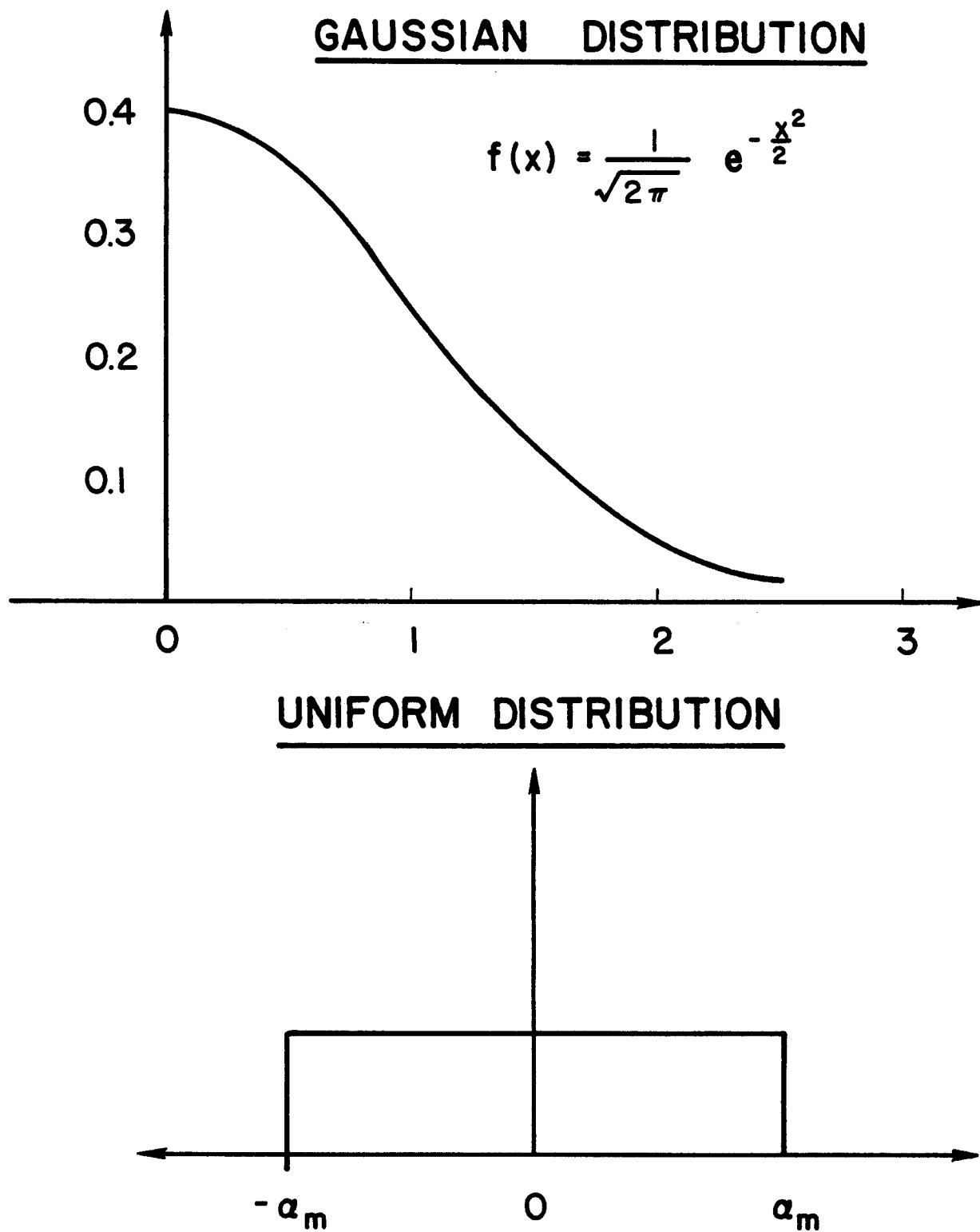


Fig. 5. Radial and angular distributions used for ion injection into z-pinch plasma channel.

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APPENDIX. ION CODE LISTING AND IMSL ROUTINE DESCRIPTIONS


```

c  each time through the output unit number is incremented by one
    il0 = il0 + 1
    if( il0 .eq. 20 ) then
        write(i6,*) ' max number of output files exceeded'
        stop
    endif
    call create( il0, outfil(il0-9), 2, -1)
c
c  initialize the random number generator seed
    random = 1
c  random = 123456.d0
c
    pi = 4. * atan(1.)
    beta0 = 0.0
    alpha0 = 0.0
    dedt = 0.0
    amps = 0.0
    b0 = 0.0
    c = 2.9979e10
    cmodel(1) = '    uniform'
    cmodel(2) = '    tapered'
    cmodel(3) = '    arbitrary'
    copt(1) = 'trajectories'
    copt(2) = ' phase space'
    copt(3) = 'radial prof1'
c
c  input the type of model ( straight or tapered channel or
c  arbitrary magnetic field with possible non-zero angular momentum)
    10 write(i6,1001)
    1001 format(
    1 '0 what type of channel calculation do you want?'/
    1 ' 0 = stop the calculation'/
    2 ' 1 = straight channel - analytic solution'/
    3 ' 2 = tapered channel - analytic solution'/
    4 ' 3 = arbitrary channel - numerical solution  ')
    read(i5,*) xmodel
    model = xmodel
c
c  is it time to stop all of this?
    if( model .eq. 0 ) then
        write(i6,*) ' all done'
        stop
    endif
c
c  type of calculation - either plot trajectories from an instantaneous
c  ion source or plot the instantaneous positions of ions from a time
c  dependent source or plot histogram of ion radial position
    write(i6,1007)
    1007 format(
    1 '0 choose the type of calculation to be done'/
    2 ' 1 = trajectories from an instantaneous source'/
    3 ' 2 = positions of ions from a time dependent source'/
    4 ' 3 = radial distribution of ions at fixed z positions  ')
    read(i5,*) xicalc
    icalc = xicalc
    if( icalc .eq. 2 ) then
        write(i6,*) ' time at which to plot the ion positions  '
        read(i5,*) tsnap
    endif
    if( icalc .eq. 3 ) then

```

```

c  number of z positions to record radial distribution
    write(i6,*)
    1 ' number of z positions to record radial distribution '
      read(i5,*) nzfix
c
c  z positions themselves
    write(i6,1011)
1011 format(
    1 ' z positions at which to plot radial distribution(cm)')/
    read(i5,*) (zfixed(k), k=1,nzfix)
    endif
c
c  initial energy and de / dt
    write(i6,*) ' initial ion energy(mev) '
    read(i5,*) e0
    if( icalc .eq. 2 ) then
        write(i6,*) ' de / dt(mev/sec) if a ramp is desired '
        read(i5,*) dedt
    endif
c
c  ion charge and mass
    write(i6,*) ' ion charge state '
    read(i5,*) qion
    write(i6,*) ' atomic weight(amu) '
    read(i5,*) atomwt
    xmion = atomwt * 1.6726e-24
c
c  channel radius, length, current or maximum b field
    write(i6,*) ' channel radius(cm) '
    read(i5,*) rchanl
    write(i6,*) ' length(cm) '
    read(i5,*) zchanl
    write(i6,*) ' current(amps) '
    read(i5,*) amps
    write(i6,*) ' or b-zero(gauss) '
    read(i5,*) b0
c
c  number of ions, spot radius, maximum divergence angles
    write(i6,*) ' number of ions in the source distribution '
    read(i5,*) xnion
    nion = xnion
    write(i6,*) ' focal spot radius(cm) '
    read(i5,*) rsourc
    write(i6,*) ' maximum divergence angle(rad) in plane '
    read(i5,*) alpham
    if( model .eq. 3 ) then
        write(i6,*) ' maximum divergence angle(rad) out of plane '
        read(i5,*) betam
    endif
c
c  maximum time and number of times to evaluate
    if( icalc .eq. 1 ) then
        write(i6,1005)
1005 format(
    1 '0 maximum time to run the problem ',
    2 'and number of times to evaluate')/
        else if( icalc .eq. 2 ) then
            write(i6,1012)
1012 format(
    1 '0 maximum time that source is turned on ',
    2 ' and number of times to evaluate')/

```

```

    else
    endif

c
    if( icalc .eq. 1 .or. icalc .eq. 2 ) then
    read(i5,*) timmax, xntime
    ntime = xntime
    endif

c
c compute terms used for all models
v0min = sqrt(2. * 1.6022e-6 * e0 / xmion)
if( dedt .eq. 0.0 ) then
    emax = e0
    vmax = v0min
    dvdt = 0.0
else
    emax = e0 + dedt * timmax
    vmax = sqrt( 2. * 1.6022e-6 * emax / xmion )
    dvdt = (vmax - v0min) / timmax
endif
if( amps .ne. 0.0 ) then
    currnt = 3.e9 * amps
    b0 = 2. * currnt / (c * rchanl)
else
    currnt = 0.5 * b0 * c * rchanl
endif
wcb = 4.8032e-10 * qion * b0 / (xmion * c)
wbeta = sqrt(wcb * v0min / rchanl)
if( ntime .ne. 0 ) deltatt = timmax / ntime
trap = sqrt(currnt * qion * c / (4.71e16 * atomwt * v0min))
rchsq = rchanl ** 2

c
c summarize the input
if( icalc .eq. 1 ) then
write(i6,1020)
1 cmodel(model),copt(icalc),qion,atomwt,e0,
2 v0min,nion,rsourc,alpham
1020 format(
1 '0 type of channel.....',a/
2 ' type of calculation.....',a/
3 ' ion charge.....',f12.3/
4 ' ion atomic weight.....',f12.3/
5 ' ion energy(mev).....',f12.3/
6 ' ion velocity(cm/sec).....',lpl12.4/
7 ' number of ion trajectories.....',il2/
8 ' ion source focal radius(cm).....',el2.4/
9 ' ion source maximum divergence(rad)..' ,el2.4)
write(i6,1021)
1 rchanl,zchanl,amps,b0,timmax,ntime,deltatt
1021 format(
1 ' channel radius(cm).....',0plf12.3/
2 ' channel length(cm).....',f12.3/
3 ' channel current(amperes).....',lpl12.4/
4 ' maximum magnetic field(gauss).....',el2.4/
5 ' maximum time to plot trajectory(sec)',el2.4/
6 ' number of times to evaluate traj....',il2/
7 ' timestep for trajectory calc.....',el2.4)

c
    else if( icalc .eq. 2 ) then
    write(i6,1022)
1 cmodel(model),copt(icalc),qion,atomwt,e0,dedt,
2 v0min,dvdt,nion,timmax,ntime,deltatt,rsourc,alpham,tsnap

```

```

1022 format(
1 '0 type of channel.....',a/
2 ' type of calculation.....',a/
3 ' ion charge.....',f12.3/
4 ' ion atomic weight.....',f12.3/
5 ' ion energy(mev).....',f12.3/
5 ' ion energy ramp slope(mev/sec).....',lple12.4/
6 ' ion velocity(cm/sec).....',lple12.4/
6 ' ion velocity ramp slope(cm/sec**2)..' ,el2.4/
7 ' number of ion trajectories.....',il2/
5 ' ion source pulse time(sec).....',el2.4/
6 ' number of times to evaluate source..' ,il2/
7 ' timestep for source calc(sec).....',el2.4/
8 ' ion source focal radius(cm).....',el2.4/
9 ' ion source maximum divergence(rad)..' ,el2.4/
1 ' time to plot ion positions(sec).....',el2.4)
write(i6,1023)
1 rchan1,zchan1,amps,b0
1023 format(
1 ' channel radius(cm).....',f12.3/
2 ' channel length(cm).....',f12.3/
3 ' channel current(amperes).....',lple12.4/
4 ' maximum magnetic field(gauss).....',el2.4)
c
else if( icalc .eq. 3 ) then
write(i6,1024) (k,zfixed(k), k=1,nzfix)
1024 format(
1 ' zfixed(cm)....(' ,i2,').....', lple12.4)
write(i6,1025) cmodel(model), copt(icalc),
1 e0, qion, atomwt, rchan1, zchan1,
1 amps, b0, nion, rsourc, alphas, betam
1025 format(
1 '0 type of channel.....',a/
2 ' type of calculation.....',a/
2 ' ion energy(mev).....', lple12.4/
3 ' ion charge.....', el2.4/
4 ' atomic weight(amu).....', el2.4/
5 ' channel radius(cm).....', el2.4/
6 ' channel length(cm).....', el2.4/
7 ' current(amps).....', el2.4/
8 ' magnetic field(gauss).....', el2.4/
9 ' number of ions in source.....', il2/
2 ' focal spot radius(cm).....', el2.4/
1 ' max. divergence angle in plane(rad)..' , el2.4/
2 ' max. divergence angle out of plane...' , el2.4)
write(i6,1026) xmion, v0min, currnt, wcb, wbeta
1026 format(' '/
1 ' ion mass(g).....', lple12.4/
2 ' ion velocity(cm/sec).....', el2.4/
3 ' current(statamps).....', el2.4/
5 ' wcb(1/sec).....', el2.4/
6 ' betatron freq(1/sec).....', el2.4)
else
endif

```

c

```

c choose the channel model
if( model .eq. 1 ) then
call strait
else if( model .eq. 2 ) then
call taper
else if( model .eq. 3 ) then

```

```

        call arbitr
    else
        write(i6,*) ' error in choice of model, model =', model
    endif
c
c loop back to the beginning for another calculation
    goto 1
c
999 stop
end
subroutine fcnj(n,x,y,pd)
integer n
real y(n), pd(n,n), x
return
end
subroutine ionsrc(
1 rsourc,alpham,betam,
3 x0,alpha0,beta0)
c
c this subroutine chooses an ion x position, x0, and an angle of
c injection in the x-z plane, alpha0, and an angle of injection out of
c the x-z plane, beta0, into the channel by sampling from a gaussian
c distribution in position and uniform distributions in angle.
c
    use seed
    use bugs
c
c sample the distribution for the position
    x0 = rsourc * sqrt(-2. * (alog(rand(random) + 1.e-10)))
c
c select the angles
    alpha0 = alpham * (1. - 2. * rand(random))
    if( betam .ne. 0.0 )
1      beta0 = betam * (1. - 2. * rand(random))
c
c debug output
    if( debug(5) ) then
        write(idbug,*) ' ionsrc - rsourc,alpham,betam,x0,alpha0,beta0'
        write(idbug,*) rsourc, alpham, betam, x0, alpha0, beta0
    endif
c
c all done
    return
end
subroutine arbitr
c
c this subroutine computes ion trajectories or positions using
c an arbitrary magnetic field profile b(r,z) or b(x,y,z) and
c ion beams with non-zero angular momentum
c
    use all
    use seed
    use solve
    use save
    use bugs
c
    parameter ( nsmax = 500 )
    external fcn6, fcnj
c
c set up predictor-corrector solver parameters
    numeqn = 6

```

```

        tol = 5.e-4
        meth = 1
        miter = 0
c
c  get the floating point form of the number of time steps
        fnsmax = nsmax
c
c  first get the numeric constant in the differential equations
        qimic = 4.8032e-10 * qion / (xmion * c)
c
c  set velocity scale factor for no out of plane vvelocity
        sfactr = 1.0
c
c  choose the type of calculation to be done
        if( icalc .eq. 1 ) then
c
c  we are computing the trajectories of ions from an
c  instantaneous source
c
c  compute some terms that do not depend on r0 and alpha0
        v0 = v0min
        lost = 0
c
c  loop over "nion" ions from the source
        do 150 ni = 1,nion
c
c  get the radius and angle of injection of an ion
        call ionsrc(
            1 rsourc,alpham,betam,
            3 r0,alpha0,beta0)
c
c  reset the velocity scale factor if there is out of plane velocity
        if( betam .ne. 0.0 )
            1 sfactr = 1. / sqrt(1. + sin(beta0)**2)
c
c  loop over "ntime" times to get r(t) and z(t) positions to plot
        t = 0.0
        z(1) = 0.0
        r(1) = r0
c
c  get the initial conditions for the dgear solver
c  y(1)=x, y(2)=vx, y(3)=y, y(4)=vy, y(5)=z, y(6)=vz, x=time
        y(1) = r0
        y(2) = v0 * sin(alpha0) * sfactr
        y(3) = 0.
        y(4) = v0 * sin(beta0) * sfactr
        y(5) = 0.
        y(6) = v0 * cos(alpha0) * sfactr
        x = 0.
        index = 1
        dt0 = deltat * 0.1
        do 100 nt = 2,ntime+1
            t = t + deltat
            xend = t
            call dgear(
a numeqn,fcn6,fcnj,x,dt0,y,xend,tol,meth,miter,index,
b iwk,wk,ier)
            if( ier .gt. 67 ) then
                write(i6,*) ' error in dgear ier=',ier
                stop
            endif

```

```

      if( betam .eq. 0.0 ) then
        r(nt) = y(1)
      else
        r(nt) = sqrt( y(1)**2 + y(3)**2 )
      endif
      z(nt) = y(5)
      if( abs(r(nt)) .gt. rchanl ) then
        npts = nt
        lost = lost + 1
        goto 125
      endif
100 continue
      npts = ntime + 1
125 continue
c
c debug output
      if( debug(4) ) then
        write(idebug,1000) npts,lost,(z(i),r(i), i=1,npts)
1000 format(2il2,(lp2el2.4))
      endif
c
c save trajectory for plotting
      write(il0,1100) npts
      write(il0,1101) (z(i),r(i), i=1,npts)
1100 format(il0)
1101 format(lp12el10.2)
150 continue
c
c write summary of calculation
      frac = float(nion - lost) / float(nion)
      write(i6,1102) nion, lost, frac
1102 format('0 ions injected.....', i8/
1       '   ions lost from channel.....', i8/
2       ' fraction successfully propagated..', lp1el12.4)
ccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
c
else if( icalc .eq. 2 ) then
c
c we are computing the z and r positions of ions from a
c time dependent source
c
c loop over "ntime" source times
      sfactr = 1.0
      n = 1
      tprime = -deltat
      do 250 ntp = 1,ntime
        tprime = tprime + deltat
c
c loop over "nion" source ions at this time
        do 225 ni = 1,nion
c
c get the radius and angle of injection of an ion
          call ionsrc(
            1 rsourc,alpha0,betam,
            3 r0,alpha0,beta0)
c
c reset velocity scale factor if there is out of plane velocity
          if( betam .ne. 0.0 )
            1 sfactr = 1. / sqrt( 1. + sin(beta0)**2 )

```



```

      v0 = v0min
      sfactr = 1.0
      do 400 k = 1,nzfix
      do 400 j = 1,10
        rhist(j,k) = rchan1 * (j / 10.)
400    continue
c
c  loop over "nion" ions from the source
      do 450 n = 1,nion
c
c  get the initial positions and angles of injection of an ion
c  it is assumed to be injected in the x-z plane so y0 = 0,
c  but it can have an out of plane velocity vy at an angle beta0
      call ionsrc(
        1 rsourc, alpham, betam,
        3 r0, alpha0, beta0)
c
c  get the scale factor so that the energy of every ion is the
c  same when there is an out of plane component of the velocity
      if( betam .ne. 0.0 )
        1 sfactr = 1. / sqrt(1. + sin(beta0)**2)
c
c  get the initial conditions for the dgear solver
c  y(1)=x, y(2)=vx, y(3)=y, y(4)=vy, y(5)=z, y(6)=vz, x=time
      y(1) = r0
      y(2) = v0 * sin(alpha0) * sfactr
      y(3) = 0.
      y(4) = v0 * sin(beta0) * sfactr
      y(5) = 0.
      y(6) = v0 * cos(alpha0) * sfactr
      vz0 = y(6)
      x = 0.
c
c  get the initial angular momentum
      amom0 = y(1) * y(4)
c
c  set dgear parameters for the first time step
      dt0 = zfixed(1) / (5000. * vz0)
      index = 1
c
c  for each plane at zfixed(k)
      do 425 k = 1,nzfix
c
c  compute the time to reach zfixed(k)
      xend = zfixed(k) / vz0
c
c  integrate the equations of motion up to the desired position
      call dgear(
        a numeqn,fcn6,fcnj,x,dt0,y,xend,tol,meth,miter,index,
        b iwk,wk,ier)
c
c  check for problems
      if( ier .gt. 67 ) then
        write(i6,*) 'error in dgear -- ier=', ier
        stop
      endif
c
c  compute the ion radial position
      if( betam .eq. 0.0 ) then
        rfixed = y(1)
      else

```

```

        rfixed = sqrt( y(1)**2 + y(3)**2 )
    endif
c
c compute the ion speed to compare to the initial speed
c     v0fix = sqrt( y(2)**2 + y(4)**2 + y(6)**2 )
c     vfrac = (v0 - v0fix) / v0
c     if( abs(vfrac) .gt. 0.2 )
c     1         write(i6,*) 'v0=',v0,' v0fix=',v0fix
c
c compute the angular momentum to compare to the initial
c     amom = y(1) * y(4) - y(3) * y(2)
c     amfrac = (amom0 - amom) / amom0
c     if( abs(amfrac) .gt. 0.2 )
c     1         write(i6,*) 'amom0=',amom0,' amom=',amom
c
c put the ion into the radial particle distribution
c     do 420 j = 1,10
c         if( rfixed .lt. rhist(j,k) ) then
c             phist(j,k) = phist(j,k) + 1.
c             goto 425
c         endif
c     420 continue
c
c end loop over zfixed(k)
c     425 continue
c
c end loop over ions from source
c     450 continue
c
c compute the fluence distribution from the particle distribution
c     do 460 k = 1,nzfix
c         fhist(1,k) = phist(1,k) / (pi * rhist(1,k)**2)
c         do 460 j = 2,10
c             fhist(j,k) = phist(j,k) /
c     1         (pi * (rhist(j,k)**2 - rhist(j-1,k)**2))
c     460 continue
c
c save the distributions for plotting
c     write(i10,1300) nzfix
c     write(i10,1301) ((rhist(j,k), j=1,10), k=1,nzfix)
c     write(i10,1301) ((phist(j,k), j=1,10), k=1,nzfix)
c     write(i10,1301) ((fhist(j,k), j=1,10), k=1,nzfix)
c 1300 format(i10)
c 1301 format(1p10e10.2)
c
c write a summary of the calculation
c     do 500 k = 1,nzfix
c         sum = 0.0
c         do 490 j = 1,10
c             sum = sum + phist(j,k)
c     490 continue
c         frac = sum / float(nion)
c         write(i6,1400) nion, sum, frac
c         write(i6,1401) (rhist(j,k), j=1,10), (phist(j,k), j=1,10)
c         write(i6,1402) (rhist(j,k), j=1,10), (fhist(j,k), j=1,10)
c     500 continue
c 1400 format('0 number of source ions.....', i8/
c     1         ' number of ions in distribution.', f8.0/
c     2         ' fraction of ions reaching plane', 1p1e12.4)
c 1401 format('0 particle distribution.....'/(1p10e10.2))
c 1402 format('0 fluence distribution.....'/(1p10e10.2))

```



```

        if( icalc .eq. 1 ) then
c
c we are computing the trajectories of ions from an instantaneous
c source
c
c compute some more terms that do not depend on r0 and alpha0
    v0 = v0min
    lost = 0
c
c loop over "nion" ions from the source
    do 150 ni = 1,nion
c
c get the radius and angle of injection of an ion
    call ionsrc(
        1 rsrc,alpham,betam,
        3 r0,alpha0,beta0)
c
c determine whether the ion is trapped or whether it escapes the
c channel b - field before any trajectory is computed
    trapal = trap * sqrt( 1.0 - min((r0/rchanl)**2, 1.0) )
    if( alpha0 .gt. trapal ) then
        lost = lost + 1
        goto 150
    endif
c
c get some more terms that depend on r0 and alpha0
    cosa0 = cos(alpha0)
    sina0 = sin(alpha0)
    tana0 = sina0 / cosa0
    bfreq = sqrt(wcb * v0 * cosa0 / rchanl)
    rbar = sqrt(r0**2 + rchanl * v0 * sina0**2 / (wcb * cosa0))
    phi = atan(-sqrt(rchanl * v0 * cosa0 / (wcb * r0**2))
        1 * tana0)
    wb = bfreq * (1. - wcb * rbar**2 / (16. * rchanl * v0 * cosa0)
        1 + 0.25 * tana0**2)
c
    z1 = v0 * cosa0 - wcb / (4. * rchanl) * rbar**2 * cos(2. * phi)
    z2 = rbar**2 / (8. * rchanl) * sqrt(rchanl * wcb / (v0 * cosa0))
    z3 = sin(2. * phi)
c
c loop over ntime times to get z(t) and r(t) positions to plot
    t = 0.0
    tprime = 0.0
    z(1) = 0.0
    r(1) = r0
    do 100 nt = 2,ntime+1
        t = t + deltat
        z(nt) = z1 * t + z2 * (sin(2. * (wb * t + phi)) - z3)
        r(nt) = rbar * cos(wb * t + phi)
        if( abs(r(nt)) .gt. rchanl ) then
            npts = nt
            lost = lost + 1
            goto 125
        endif
    100 continue
    npts = ntime+1
    125 continue
c
c debug output
    if( debug(2) ) then
        write(idbug,1000) npts,lost,(z(i),r(i), i=1,npts)

```



```

c  always be less than the actual time
    t0 = zfixed(k) / v0
c
c  get the computed z position at this estimated time
    z0 = z1 * t0 + z2 * (sin(2. * (wb * t0 + phi)) - z3)
c
c  estimate a time step to allow us to approach the correct z-fixed
    t1 = t0 * (zfixed(k) / z0)
    deltat = (t1 - t0) / 100.
c
c  find the correct time for an ion to reach zfixed
    do 425 i = 1,1000
        t = t0 + i * deltat
        ztest = z1 * t + z2 * (sin(2. * (wb * t + phi)) - z3)
        if( ztest .ge. zfixed(k) ) goto 430
    425 continue
c
c  if we reach here then we did not find t corresponding to zfixed
    write(i6,*) 'did not find time for z-fixed'
    stop
c
c  we have found the time, now evaluate the radial position
    430 continue
        rfixed = abs(rbar * cos(wb * t + phi))
c
c  put the ion into the radial particle distribution
    do 440 j = 1,10
        if( rfixed .lt. rhist(j,k) ) then
            phist(j,k) = phist(j,k) + 1.0
            goto 445
        endif
    440 continue
    445 continue
    450 continue
c
c  compute the fluence distribution from the particle distribution
    do 480 k = 1,nzfix
        fhist(1,k) = phist(1,k) / (pi * rhist(1,k)**2)
        do 470 j = 2,10
            fhist(j,k) = phist(j,k) /
                1 (pi * (rhist(j,k)**2 - rhist(j-1,k)**2))
        470 continue
    480 continue
c
c  save the distributions for plotting
    write(i10,1300) nzfix
    write(i10,1301) ((rhist(j,k), j=1,10), k=1,nzfix)
    write(i10,1301) ((phist(j,k), j=1,10), k=1,nzfix)
    write(i10,1301) ((fhist(j,k), j=1,10), k=1,nzfix)
    1300 format(i10)
    1301 format(lp10e10.2)
c
c  write a summary of the calculation
    do 500 k = 1,nzfix
        sum = 0.0
        do 490 j = 1,10
            sum = sum + phist(j,k)
        490 continue
        frac = (sum / float(nion))
        write(i6,1400) nion, sum, frac
        write(i6,1401) (rhist(j,k), j=1,10), (phist(j,k), j=1,10)

```

```

write(i6,l402)(rhist(j,k), j=1,10), (fhist(j,k), j=1,10)
500 continue
1400 format('0 number of source ions.....', i8/
      1      ' number of ions in distribution.', f8.0/
      2      ' fraction of ions reaching plane', lpl12.4)
1401 format('0 particle distribution.....'/(lp10el0.2))
1402 format('0 fluence distribution.....'/(lp10el0.2))
ccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
c
ccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
      else
c
c   a place to put other options
      endif
      return
      end
      subroutine bxyz(
1 targ,xarg,yarg,zarg,b0,rchanl,rchsq,
2
3 bx,by,bz)
c
c this subroutine computes b-x,y,z and must be supplied
c by the user.
c
      use bugs
c
c see whether we are inside or outside the channel
      xysq = xarg**2 + yarg**2
      if( xysq .lt. rchsq ) then
c we are inside
c       bx = b0 * yarg / rchanl
c       by = b0 * xarg / rchanl
          bx = b0 * (yarg / rchanl) ** 5
          by = b0 * (xarg / rchanl) ** 5
          bz = 0.0
      else
c we are outside
          if( yarg .ne. 0. ) then
              bx = b0 * rchanl / yarg
          else
              bx = 0.
          endif
          if( xarg .ne. 0. ) then
              by = b0 * rchanl / xarg
          else
              by = 0.
          endif
          bz = 0.0
      endif
c
c debug output
      if( debug(7) ) then
          write(idbug,*)
1         ' bxyz - targ,xarg,yarg,zarg,b0,rchanl,bx,by,bz'
          write(idbug,*) targ,xarg,yarg,zarg,b0,rchanl,bx,by,bz
      endif
c
      return
      end
      subroutine fcns6(
1 n,x,y,

```

```

      2
      3 yprime)
c
c  this subroutine provides the imsl library gear routine
c  (dgear) with the right hand sides of the six o.d.e.'s to
c  be solved
c
      real y(n), yprime(n)
c
      use all
      use bugs
c
c  first call the bxyz routine to compute the field at position
c  x = y(1), y = y(3), and z = y(5) at time = x.
      call bxyz(
1    x,y(1),y(3),y(5),b0,rchan1,rchsqr,
2
3    bx,by,bz)
c
c  now compute the right hand sides
      yprime(1) = y(2)
      yprime(2) = qimic * (y(4) * bz - y(6) * by)
      yprime(3) = y(4)
      yprime(4) = qimic * (y(2) * bz - y(6) * bx)
      yprime(5) = y(6)
      yprime(6) = qimic * (y(2) * by - y(4) * bx)
c
c  do we want debug output
      if( debug(6) ) then
1000      write(idbug,1000) (y(i), i=1,6)
           format(' y(i)=' ,lp6el2.4)
1001      write(idbug,1001) (yprime(i), i=1,6)
           format(' yprime(i)=' ,lp6el2.4)
1002      write(idbug,1002) x,bx,by,bz,qimic
           format(' x=' ,lp1el2.4,' bx=' ,el2.4,' by=' ,el2.4,
1           ' bz=' ,el2.4,' qimic=' ,el2.4)
      endif
c
c  all done
      return
      end

```